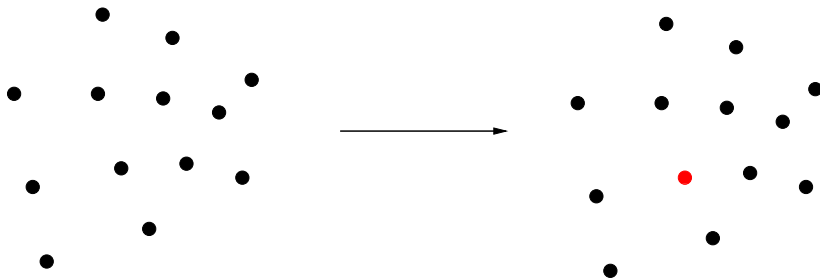


Leader Election in Swarms of Deterministic Robots

Franck Petit

LiP6, UPMC Paris 6

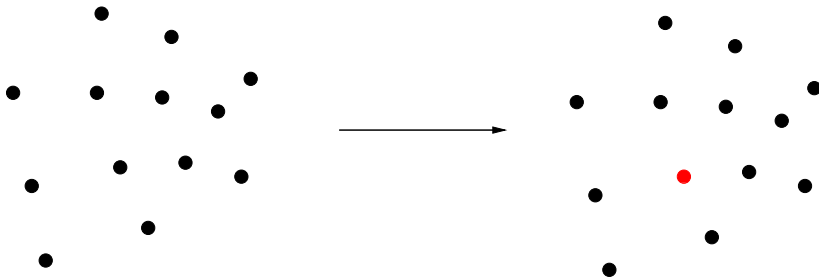
Problem



Question

Given a swarm of n robots, what are the **minimal geometric conditions** to be able to **deterministically** agree on a single robot?

Problem



Question

Given a swarm of n robots, what are the **minimal geometric conditions** to be able to **deterministically** agree on a single robot?

Previous Works

SoD and Chirality

[Flocchini et al., 1999]

A solution exists for **any n** .

SoD and No Chirality

[Flocchini et al., 2001]

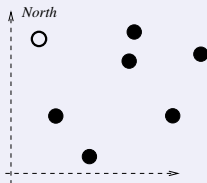
A solution exists if **n is odd**.

Previous Works

SoD and Chirality

[Flocchini et al., 1999]

A solution exists for **any** n .



SoD and No Chirality

[Flocchini et al., 2001]

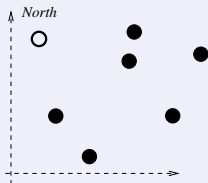
A solution exists if n is **odd**.

Previous Works

SoD and Chirality

[Flocchini et al., 1999]

A solution exists for **any** n .



SoD and No Chirality

[Flocchini et al., 2001]

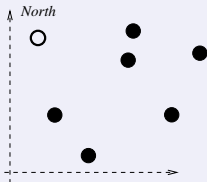
A solution exists if n is **odd**.

Previous Works

SoD and Chirality

[Flocchini et al., 1999]

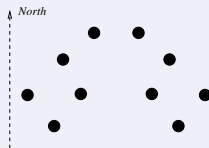
A solution exists for **any n** .



SoD and No Chirality

[Flocchini et al., 2001]

A solution exists if **n is odd**.

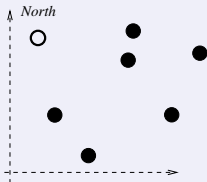


Previous Works

SoD and Chirality

[Flocchini et al., 1999]

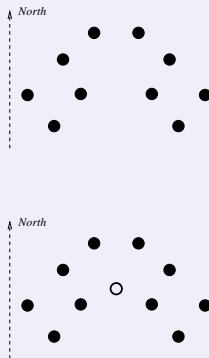
A solution exists for **any** n .



SoD and No Chirality

[Flocchini et al., 2001]

A solution exists if n is **odd**.



Previous Works

No SoD

[Prencipe 2002]

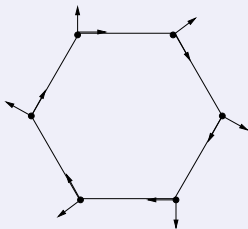
Impossible in general.

Previous Works

No SoD

[Prencipe 2002]

Impossible in general.



In such a configuration, it is not possible to break the symmetry.

Leader Election With No Sense of Direction

Question

Assuming no sense of direction (with or without chirality), what are the **geometric conditions** to be able to **deterministically** agree on a single robot?

To answer to this question, we need tools from the theory on Combinatoric on Words, specifically **Lyndon Words**.

Leader Election With No Sense of Direction

Question

Assuming no sense of direction (with or without chirality), what are the **geometric conditions** to be able to **deterministically** agree on a single robot?

To answer to this question, we need tools from the theory on Combinatoric on Words, specifically **Lyndon Words**.

Lyndon Words

Definition (Word)

Let $A = \{a_0, a_1, \dots, a_n\}$ be an alphabet. A word is a (possibly empty) sequence of letters in A .

$$A = \{a, b, c, d\}$$
$$abcc \quad a \quad \epsilon \quad dddddddd \equiv d^8$$

Lyndon Words

Definition (Word)

Let $A = \{a_0, a_1, \dots, a_n\}$ be an alphabet. A word is a (possibly empty) sequence of letters in A .

$$A = \{a, b, c, d\}$$
$$abcc \quad a \quad \epsilon \quad dddddddd \equiv d^8$$

Lyndon Words

Definition (Concatenation)

Let $u = a_1, \dots, a_i, \dots, a_k$ and $v = b_1, \dots, b_j, \dots, b_\ell$.

The concatenation of u and v , denoted uv , is equal to the word $a_1, \dots, a_i, \dots, a_k, b_1, \dots, b_j, \dots, b_\ell$.

$$u = UP, v = MC, uv = UPMC$$

Lyndon Words

Definition (Concatenation)

Let $u = a_1, \dots, a_i, \dots, a_k$ and $v = b_1, \dots, b_j, \dots, b_\ell$.

The concatenation of u and v , denoted uv , is equal to the word $a_1, \dots, a_i, \dots, a_k, b_1, \dots, b_j, \dots, b_\ell$.

$$u = UP, v = MC, uv = UPMC$$

Lyndon Words

Definition (Lexicographic Order)

Let A be an alphabet totally ordered by \prec , i.e., $a_0 \prec a_1 \prec \dots \prec a_n$.

A word $u = a_0a_1 \dots a_s$ is said to be *lexicographically smaller than or equal to* a word $v = b_0b_1 \dots b_t$, denoted by $u \preceq v$, iff:

- either u is a prefix of v ,
- or, $\exists k : \forall i \in [1, \dots, k - 1], a_i = b_i$ and $a_k \prec b_k$.

 $ab \preceq abc$
 $abc \preceq abc$
 $\epsilon \preceq abc$
 $abc \preceq def$

Lyndon Words

Definition (Lexicographic Order)

Let A be an alphabet totally ordered by \prec , i.e., $a_0 \prec a_1 \prec \dots \prec a_n$.

A word $u = a_0a_1 \dots a_s$ is said to be *lexicographically smaller than or equal to* a word $v = b_0b_1 \dots b_t$, denoted by $u \preceq v$, iff:

- either u is a prefix of v ,
- or, $\exists k : \forall i \in [1, \dots, k - 1], a_i = b_i$ and $a_k \prec b_k$.

 $ab \preceq abc$
 $abc \preceq abc$
 $\epsilon \preceq abc$
 $abc \preceq def$

Lyndon Words

Definition (Primitive Word)

A word u is said to be *primitive* iff $u = v^k \Rightarrow k = 1$. Otherwise, u is said to be *periodic*.

Primitive Words

ab $dabcbc$ $dcba$

Periodic Words

d^8 $bcbc$ ϵ

Lyndon Words

Definition (Primitive Word)

A word u is said to be *primitive* iff $u = v^k \Rightarrow k = 1$. Otherwise, u is said to be *periodic*.

Primitive Words

ab $dabcbc$ $dcba$

Periodic Words

d^8 $bcbc$ ϵ

Lyndon Words

Definition (Rotation)

A word u is said to be a *rotation* of a word v iff there exists two words x, y such that $u = xy$ and $v = yx$.

$$u = abcd \text{ and } v = cdab$$

$$u = abcd \text{ and } v = bcda$$

Definition (Minimality)

A word u is said to be a *minimal* iff u is lexicographically smaller than any of its rotations.

Lyndon Words

Definition (Rotation)

A word u is said to be a *rotation* of a word v iff there exists two words x, y such that $u = xy$ and $v = yx$.

$$u = abcd \text{ and } v = cdab$$

$$u = abcd \text{ and } v = bcda$$

Definition (Minimality)

A word u is said to be a *minimal* iff u is lexicographically smaller than any of its rotations.

Lyndon Words

Definition (Rotation)

A word u is said to be a *rotation* of a word v iff there exists two words x, y such that $u = xy$ and $v = yx$.

$$u = abcd \text{ and } v = cdab$$

$$u = abcd \text{ and } v = bcda$$

Definition (Minimality)

A word u is said to be a *minimal* iff u is lexicographically smaller than any of its rotations.

Lyndon Words

Definition (Lyndon Word)

A word u is a *Lyndon word* iff u is **primitive and minimal**.

Lyndon Word

abc ($abc \preceq cab$ and $abc \preceq bca$)

Not a Lyndon Word

bca ($bca \succ abc$)

Lyndon Words

Definition (Lyndon Word)

A word u is a *Lyndon word* iff u is **primitive and minimal**.

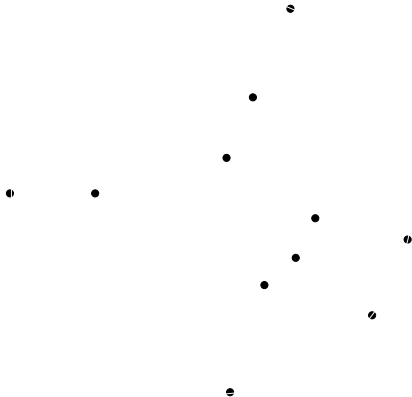
Lyndon Word

abc ($abc \preceq cab$ and $abc \preceq bca$)

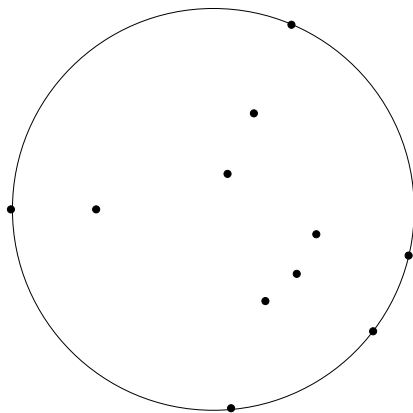
Not a Lyndon Word

bca ($bca \succ abc$)

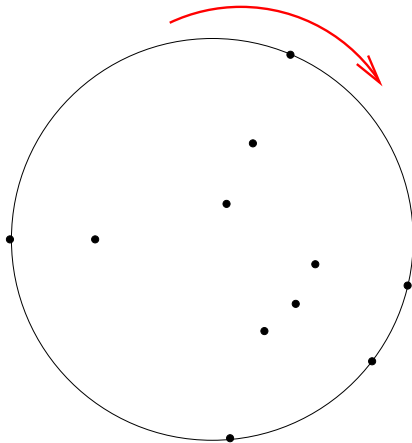
Leader Election with Chirality



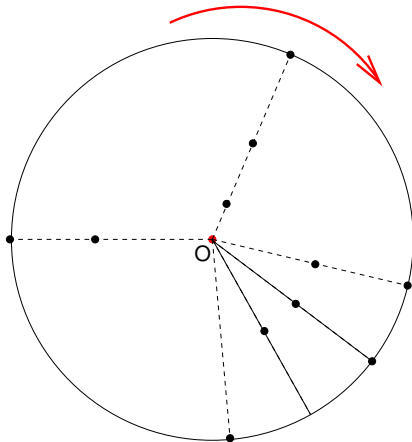
Leader Election with Chirality



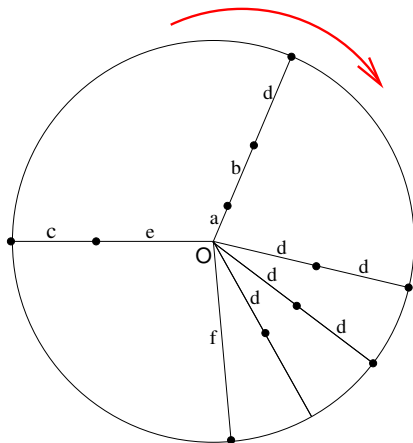
Leader Election with Chirality



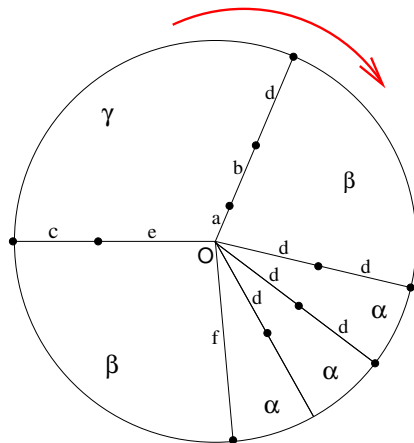
Leader Election with Chirality



Leader Election with Chirality



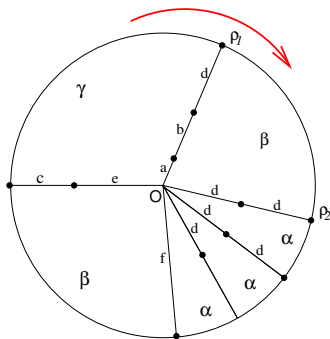
Leader Election with Chirality



Leader Election with Chirality

$$W(\rho_1) = (abc, \beta)(d^2, \alpha)^2(d, \alpha)(f, \beta)(ec, \gamma)$$

$$W(\rho_2) = (d^2, \alpha)^2(d, \alpha)(f, \beta)(ec, \gamma)(abc, \beta)$$



Lemma

If two distinct radii ρ_1 and ρ_2 exist such that both $W(\rho_1)$ and $W(\rho_2)$ are Lyndon words, then $\forall \rho, W(\rho) = (0, 0)$.

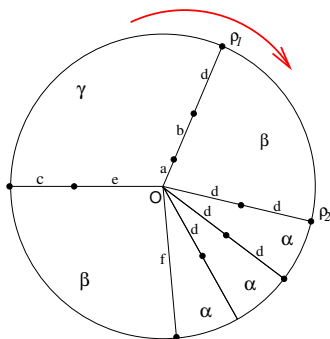
Lemma (\Rightarrow)

If there exists a radius ρ such that $W(\rho)$ is a **Lyndon word**, then the robots are able to **deterministically** agree on the same leader.

Leader Election with Chirality

$$W(\rho_1) = (abc, \beta)(d^2, \alpha)^2(d, \alpha)(f, \beta)(ec, \gamma)$$

$$W(\rho_2) = (d^2, \alpha)^2(d, \alpha)(f, \beta)(ec, \gamma)(abc, \beta)$$



Lemma

If two distinct radii ρ_1 and ρ_2 exist such that both $W(\rho_1)$ and $W(\rho_2)$ are Lyndon words, then $\forall \rho, W(\rho) = (0, 0)$.

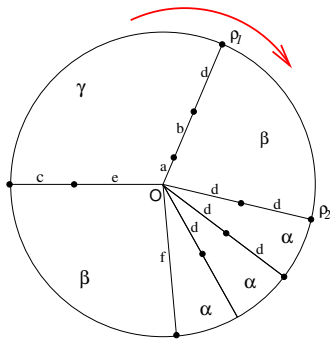
Lemma (\Rightarrow)

*If there exists a radius ρ such that $W(\rho)$ is a **Lyndon word**, then the robots are able to **deterministically** agree on the same leader.*

Leader Election with Chirality

$$W(\rho_1) = (abc, \beta)(d^2, \alpha)^2(d, \alpha)(f, \beta)(ec, \gamma)$$

$$W(\rho_2) = (d^2, \alpha)^2(d, \alpha)(f, \beta)(ec, \gamma)(abc, \beta)$$



Lemma

If two distinct radii ρ_1 and ρ_2 exist such that both $W(\rho_1)$ and $W(\rho_2)$ are Lyndon words, then $\forall \rho, W(\rho) = (0, 0)$.

Lemma (\Rightarrow)

If there exists a radius ρ such that $W(\rho)$ is a **Lyndon word**, then the robots are able to **deterministically** agree on the same leader.

Leader Election with Chirality

Lemma (\Leftarrow)

If there exists **no** radius ρ such that $W(\rho)$ is a **Lyndon word**, then the robots are **not** able to **deterministically** agree on the same leader.

Property

[Lothaire 1983]

If no rotation of a word u is a Lyndon word, then u is periodic.

Leader Election with Chirality

Lemma (\Leftarrow)

If there exists *no* radius ρ such that $W(\rho)$ is a *Lyndon word*, then the robots are *not* able to *deterministically* agree on the same leader.

Property

[Lothaire 1983]

If no rotation of a word u is a Lyndon word, then u is periodic.

Leader Election with Chirality

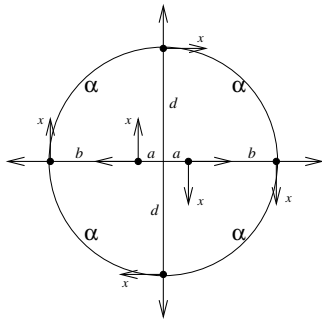
Lemma (\Leftarrow)

If there exists **no** radius ρ such that $W(\rho)$ is a **Lyndon word**, then the robots are **not** able to **deterministically** agree on the same leader.

Property

[Lothaire 1983]

If no rotation of a work u is a Lyndon word, then u is periodic.



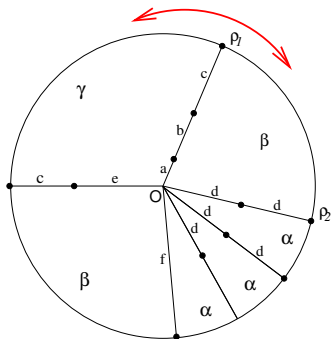
Leader Election with Chirality

Theorem

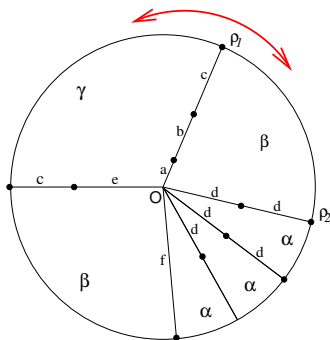
Assuming *chirality*, a swarm of robots is able to *deterministically* agree on the same leader if and only if there exists a radius ρ such that $W(\rho)$ is a *Lyndon word*.

Leader Election without Chirality

Leader Election without Chirality



Leader Election without Chirality



For each ρ , there are 2 ways to compute $W(\rho)$

$$W(\rho_1) =$$

either

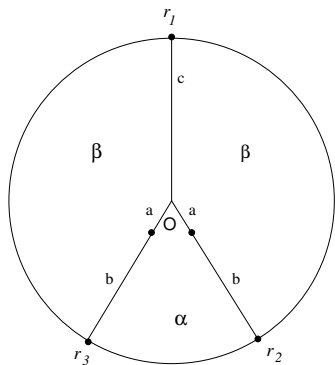
$$(abc, \beta)(d^2, \alpha)^2(d, \alpha)(f, \beta)(ec, \gamma)$$

or

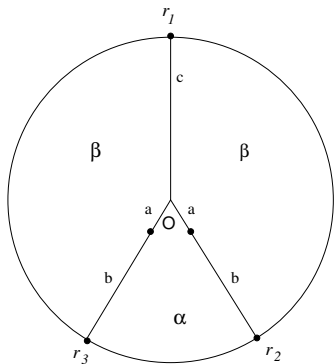
$$(abc, \gamma)(ec, \beta)(f, \alpha)(d, \alpha)(d^2, \alpha)(d^2, \beta)$$

depending on either \circlearrowleft or \circlearrowright , respectively.

Leader Election without Chirality



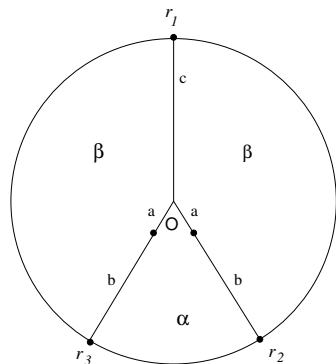
Leader Election without Chirality



The word

$W(\rho_2)^\circ = W(\rho_3)^\circ = (ab, \alpha)(ab, \beta)(c, \beta)$ is a
Lyndon word.

Leader Election without Chirality



Definition (Type of Symmetry)

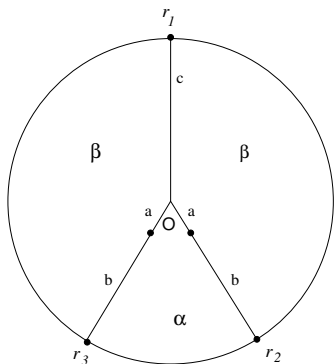
A radius ρ_i is of Type (of symmetry) **0** if there exists no radius ρ_j such that $W(\rho_i)^\circ = W(\rho_j)^\circ$. Otherwise, ρ_i is said to be of Type **1**.

A radius of Type **t** is said to be **t -symmetric**.

ρ_1 is **0**-symmetric.

ρ_2 and ρ_3 are **1**-symmetric.

Leader Election without Chirality



Definition (Type of Symmetry)

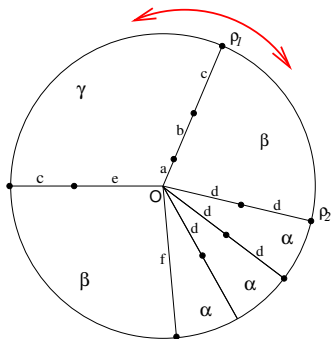
A radius ρ_i is of Type (of symmetry) **0** if there exists no radius ρ_j such that $W(\rho_i)^\circ = W(\rho_j)^\circ$. Otherwise, ρ_i is said to be of Type **1**.

A radius of Type t is said to be t -symmetric.

ρ_1 is **0**-symmetric.

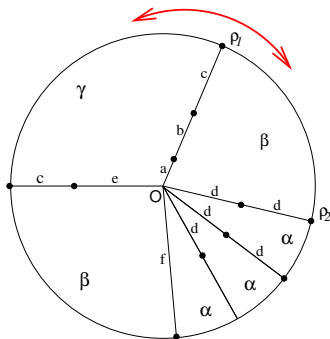
ρ_2 and ρ_3 are **1**-symmetric.

Leader Election without Chirality



For each radius ρ_i , every robot computes $W(\rho_i)^\ominus$ and $W(\rho_i)^\ominus$ of the form *(type, radiusword, angle)*.

Leader Election without Chirality

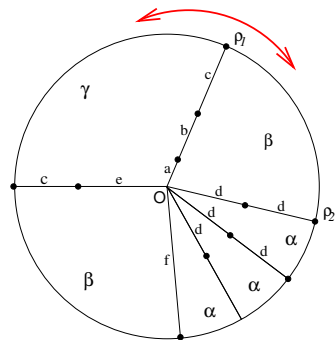


For each radius ρ_i , every robot computes $W(\rho_i)^\circ$ and $W(\rho_i)^\circ$ of the form *(type, radiusword, angle)*.

$$W(\rho_1)^\circ = (0, abc, \beta)(0, d^2, \alpha)^2(0, d, \alpha)(0, f, \beta)(0, ec, \gamma)$$

$$W(\rho_1)^\circ = (0, abc, \gamma)(0, ec, \beta)(0, f, \alpha)(0, d, \alpha)(0, d^2, \alpha)(0, d^2, \beta)$$

Leader Election without Chirality



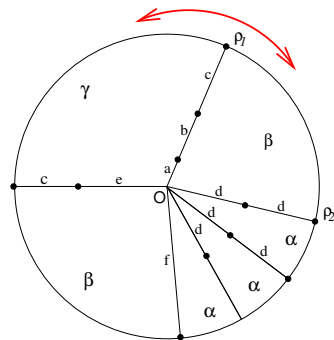
Lemma

If two distinct radii ρ_1 and ρ_2 exist such that both $W(\rho_1)$ and $W(\rho_2)$ are Lyndon words, then $\forall \rho, W(\rho) = (0, 0, 0)$.

Lemma

If there exists a pair of radii $\{\rho_1, \rho_2\}$ so that $W(\rho_i)^\circ$ or $W(\rho_i)^\circ$ is a **Lyndon word** ($i \in \{1, 2\}$), then the robots are able to **deterministically** agree on the same leader if and only if ρ_1 and ρ_2 are **0-symmetric**.

Leader Election without Chirality



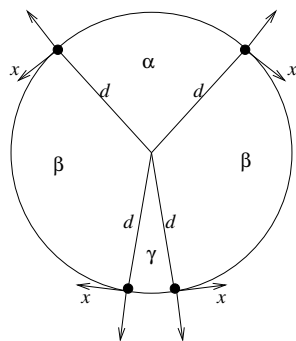
Lemma

If two distinct radii ρ_1 and ρ_2 exist such that both $W(\rho_1)$ and $W(\rho_2)$ are Lyndon words, then $\forall \rho, W(\rho) = (0, 0, 0)$.

Lemma

If there exists a pair of radii $\{\rho_1, \rho_2\}$ so that $W(\rho_i)^\circ$ or $W(\rho_i)^\circ$ is a **Lyndon word** ($i \in \{1, 2\}$), then the robots are able to **deterministically** agree on the same leader if and only if ρ_1 and ρ_2 are **0-symmetric**.

Leader Election without Chirality



No leader exists.

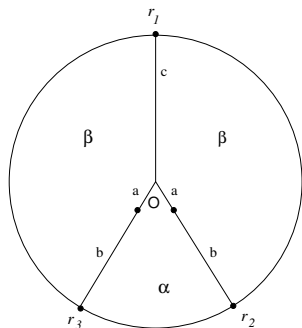
Lemma

If two distinct radii ρ_1 and ρ_2 exist such that both $W(\rho_1)$ and $W(\rho_2)$ are Lyndon words, then $\forall \rho, W(\rho) = (0, 0, 0)$.

Lemma

If there exists a pair of radii $\{\rho_1, \rho_2\}$ so that $W(\rho_i)^\circ$ or $W(\rho_i)^\circ$ is a **Lyndon word** ($i \in \{1, 2\}$), then the robots are able to **deterministically** agree on the same leader if and only if ρ_1 and ρ_2 are **0-symmetric**.

Leader Election without Chirality



The robot on ρ_1 is the leader.

Lemma

If two distinct radii ρ_1 and ρ_2 exist such that both $W(\rho_1)$ and $W(\rho_2)$ are Lyndon words, then $\forall \rho, W(\rho) = (0, 0, 0)$.

Lemma

If there exists a pair of radii $\{\rho_1, \rho_2\}$ so that $W(\rho_i)^\circ$ or $W(\rho_i)^\circ$ is a **Lyndon word** ($i \in \{1, 2\}$), then the robots are able to **deterministically** agree on the same leader if and only if ρ_1 and ρ_2 are **0-symmetric**.

Leader Election without Chirality

Theorem

Assuming *no chirality*, a swarm of robots is able to *deterministically* agree on the same leader if and only if there exists a radius ρ such that $W(\rho)$ is a *0-symmetric Lyndon word*.